## **XSENTRY - CUAV**





The XSENTRY-CUAV EOST search and tracking system is mainly used in counter UAV applications.

It is used to provide real-time reconnaissance and warning of incoming drones, UAV, aircraft etc.

The EOST act as the detection, search and tracking sensor, which can be used for standalone and also can be integrated with 3rd party C-UAV system.

## **FUNCTION**

- Search air targets ranging from 20° to 340°, support single target tracking and distance measurement, support thermal and visible camera tracking simultaneously.
- Manual and automatic tracking and ranging.
- Automatically search and alert the airspace.
- · Maintenance mode, in which the optical axis can be calibrated
- Independent air situation reporting (complete information about the target is reported to the radar display terminal via a wireless communication module)
- Positioning and orientation function (the target is reported with due north as the reference)
- Tracking video reporting function (tracking video is reported to the radar control terminal via the wireless communication module as a video stream).
- Long-range wireless air traffic transmission based on L-band single-channel portable nodes.









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|                             | XSENTF   | RY-CUAV   |               |                       |  |
|-----------------------------|--|---|---------------|-----------------------|--|
| Thermal (Search & Tracking) |  | Position Pointing Accuracy  | 0.1mrad       |                       |  |
| Detector Type               | VOX Uncooled @12μm                                 | Search Speed  | 180° / 2.8s   |                       |  |
| Detector Resolution         | 1024*1280 (1024*2560 dual-thermal mode)            | Max. Azimuth Speed  | 180°/s        |                       |  |
| Focal Length                | 75mm   | Max. Tracking Angular Velocity                                      | 20°/s         |                       |  |
| FOV                         | 9°x11° (9°x22° dual-thermal mode)                  | Max. Tracking Angular   | 40°/s²        |                       |  |
| Fps                         | 30Hz   | Acceleration  |               |                       |  |
| Visible (Tracking)          |  | Tracking Accuracy   | ≤2mrad        |                       |  |
| Image Sensor                | 1/2.5 Exmor R CMOS                                 | Target Indication Accuracy  | ≤0.6mrad      |                       |  |
| Resolution                  | 1920*1080  | Min. Smooth Tracking Angular Velocity                               | 0.05 °/s.     |                       |  |
| Focal Length                | 4.3mm ~ 129.0mm 30x optical zoom, 12x digital zoom | Ingress Protection  | IP66          |                       |  |
| Fps                         | 60Hz   | Dimension (H×W×L)   | 401×236×405mm |                       |  |
| Focal Mode                  | Auto/Manual  | Weight  | 12kg          |                       |  |
| WDR                         | Support  | Power Supply  | 26V           |                       |  |
| Day/Night                   | Auto/Manual  | Avg. Power Consumption  | 60W           |                       |  |
| Defog                       | Support  | Detection Distance  | Thermal       | Visible               |  |
| Electronic Stabilisation    | Support  | UAV (450mm)   | 1.5km         | 2km                   |  |
| DNR                         | 3D DNR   | Tactical UAV (4m+3m)  | 3.5km         | 6km                   |  |
| Laser Rangefinder           |  | Helicopter  | 8km           | 15km                  |  |
| Operating Range             | 12km   | Aircraft  | 10km          | 18km                  |  |
| Wave Length                 | 1535nm (Eye-safe class 1)                          | Multi-target search and tracking                                    |               |                       |  |
| Range Accuracy              | ±1m  | Search mode ≥20 targets (pitch-centre-fixed, orientation 0° ~360°). |               |                       |  |
| Frequency                   | 1-5Hz  |   |               | ~360°).               |  |
| Servo                       |  |   |               |                       |  |
| Azimuth Range               | 20° ~ 340°   | Tracking mode ≥2 targets (within 90 ° of azimut 30° of pitch)       |               | thin 90 ° of azimuth, |  |
| Pitch Range                 | -15 to +60°  |   | 30° OI pitch) | 50° OI pitch)         |  |